

# 1                   **Reconstruction of an extinct soundscape reveals** 2                   **ultrasonic communication in the Jurassic**

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## 6                   **Supplementary methods**

### 7 **Phylogenomic analysis**

#### 8 **Data processing, filtering, and phylogenomic analysis**

9 Adapter contamination and low-quality bases were removed using Trimmomatic<sup>85</sup>, and  
10 trimmed reads were assembled de novo using SOAPdenovo2<sup>86</sup>. To assign assembled sequences  
11 to orthologous loci with high specificity, we used Orthograph with an Orthoptera-focused  
12 ortholog database. Orthograph<sup>87</sup> was used to screen assemblies and identify putative orthologs,  
13 thereby minimizing inclusion of paralogs and non-target contaminants while standardizing  
14 locus identities across samples. Thousands of recovered loci are generated at this step.

#### 15 **Ortholog alignment construction and orthology quality control**

16 Orthologous sequences were subsequently processed through the 1KITE cleaning pipeline to  
17 further curate orthology and standardize locus sets<sup>88</sup>. This step included additional orthology  
18 checking and cleaning procedures, followed by multiple sequence alignment of each  
19 orthologous locus using MAFFT (v7.130b)<sup>89</sup>. The resulting per-locus alignments formed the  
20 initial matrix for downstream filtering and phylogenetic inference.

#### 21 **Site-level filtering and sequence-level cleanup**

22 We filtered alignments a custom python script (01\_filter\_gap\_alignments.py) allowing up to  
23 90% gaps per column of the alignment, and up 35% missing data (within a solid empirical  
24 threshold)<sup>6</sup> per row with a minimum of 100bp and at least 4 taxa present - this was done as  
25 utilizing small alignments and limited filtering allows for true signal to be retained<sup>90</sup>. After  
26 filtering, to deal with initial transcriptomic biases (these data consist of thousands more genes  
27 than typical hybrid capture, and can thus overwhelm the lesser amount of data and  
28 transcriptomic data can be drawn together artificially) we used our custom  
29 transcript\_only\_filter.py to remove alignments consisting of only transcriptomic sequences.

## 30 **Gene tree inference and rogue taxon mitigation**

31 To assess gene-level topological variation and identify problematic taxa, we inferred a  
32 maximum likelihood gene tree for each filtered locus alignment in RAxML-NG v1.2.0<sup>91</sup>. These  
33 were run with the GTR+G model and 100 bootstrap trees. These per-locus trees were used to  
34 examine patterns of concordance and conflict among loci and to identify sequences exhibiting  
35 anomalous placement likely driven by missing data, alignment artifacts, or contamination. We  
36 then applied TreeShrink v1.3.9<sup>92</sup> to the gene tree set to detect and mitigate the impact of rogue  
37 taxa (i.e., taxa producing unusually long branches or unstable placements across loci). Taxa  
38 flagged as likely to distort inference were removed or down-weighted according to the  
39 TreeShrink workflow<sup>92</sup>, thereby improving robustness of downstream concatenated and time-  
40 calibrated analyses. After TreeShrink, we took updated alignments (adjusted by the program)  
41 and re-estimated gene trees with rogue taxa removed.

## 42 **Monophyly screening to prevent technology-driven clustering**

43 Because our dataset combines hybrid capture and transcriptome-derived sequences, we  
44 implemented an additional safeguard to ensure that sequences were not clustering artificially  
45 by data type rather than evolutionary history. We used a custom monophyly filter  
46 (final\_monophyly\_checker.py) to test whether transcriptome-derived sequences formed  
47 spurious monophyletic groups across loci or in the concatenated topology. Loci or taxa showing  
48 evidence of technology-associated, artificial monophyletic grouping by data type were flagged  
49 and removed prior to final inference, similarly to Frandsen et al.<sup>93</sup>.

## 50 **Concatenated phylogenomic inference and partition optimization**

51 We concatenated the final 1,077 locus alignments into a supermatrix using AMAS.py script<sup>94</sup>  
52 and generated an initial partitioning scheme with one partition per orthologous locus. We  
53 inferred the maximum likelihood phylogeny of the 625,593 bp supermatrix in IQ-TREE  
54 v3.0.1<sup>95</sup> using comprehensive model and partition optimization. Specifically, we used  
55 ModelFinder<sup>96</sup> with partition merging enabled (MFP + MERGE) and the greedy algorithm  
56 (rcluster) with parameter 10, allowing the data to determine an optimised, reduced partition  
57 scheme<sup>97</sup>. Node support was assessed with 1,000 ultrafast bootstrap replicates<sup>98</sup> with the “-  
58 bnni” flag added to reduce the impact of known ultrafast bootstrap inflation toward values of  
59 100 and 1,000 SH-aLRT replicates, providing complementary measures of branch reliability.

## 60 **Acoustic and wing motion recordings**

61 Stridulatory wing movements and the associated sound production were recorded from  
62 *Cyphoderris monstrosa* (3 males), *Tarragoilus diuturnus* (2 males), *Gryllus bimaculatus* (9  
63 males), and, and *Panacanthus pallicornis* (8 males) using protocols well established by the  
64 authors. Acoustic signals were captured using a calibrated 1/8" microphone (Brüel & Kjær Type  
65 4138 connected to a preamplifier Type 2633) and amplified with a B&K1708 conditioning  
66 amplifier (Brüel & Kjaer, Nærum, Denmark). Wing movements were monitored using an opto-  
67 electronic device<sup>99,100</sup>. To facilitate recordings from dorsal or posterior views, a piece of  
68 reflective tape (Scotchlite 7610 and 8850, 3M) was affixed to the left tegmen. Sound and wing  
69 movement signals were recorded on separate channels using PSV acquisition software (Polytec  
70 GmbH, Waldbronn, Germany), which employed a National Instruments (NI) acquisition board.  
71 A high-pass filter was set at 2 kHz for the sound recordings, a low-pass filter with a cut-off at  
72 5 kHz for the wing motion, and a sampling frequency of 512 kHz. Experimental conditions  
73 were maintained at a temperature of 24-26 °C and a relative humidity of 35–40%.

#### 74 **Laser Doppler Vibrometry**

75 Wing resonance was measured in the same species above [*Cyphoderris monstrosa* (3 males),  
76 *Tarragoilus diuturnus* (8 males), *Gryllus bimaculatus* (47 males), and, and *Panacanthus*  
77 *pallicornis* (8 males)], using micro-scanning laser Doppler vibrometry (LDV; PSV-500,  
78 Polytec GmbH, Waldbronn, Germany). In these experiments, the insect was mounted on a  
79 horizontal brass platform following the methodology outlined by Montealegre-Z et al.<sup>100</sup>. The  
80 dorsal region of the wings was stimulated using synthetic sound and scanned with the LDV  
81 across a grid of approximately 1,000 points, utilising a sample rate of 128 kHz and averaging  
82 three measurements per point. The acoustic stimulation comprised broadband periodic chirps  
83 within the frequency range of 1.5-50 kHz. The sound pressure of the stimulus was calibrated to  
84 ensure a consistent sound pressure level (SPL) of  $60 \pm 1.5$  dB (re. 20) throughout the  
85 experimental range. Acoustic signals were generated by the internal data acquisition board of  
86 the PSV (PCI-4451; National Instruments, Austin, TX, USA), amplified (A-400, Pioneer,  
87 Kawasaki, Japan), and transmitted to a loudspeaker (Ultrasonic Dynamic Speaker Vifa, Avisoft  
88 Bioacoustics, Glienicke, Germany) located 30 cm from the specimen. The reference signal was  
89 recorded with a 1/8" condenser microphone placed horizontally near the wings (Brüel & Kjaer,  
90 4138-A-015, and preamplifier model 2670, Brüel & Kjaer, Nærum, Denmark).

#### 91 **Micro-CT scanning of the hearing system in living forms**

92 Specimens were scanned using a SkyScan 1172  $\mu$ -CT scanner (12.9  $\mu$ m voxel size, 55 kV  
93 source voltage, 200  $\mu$ A source current, 200 ms exposure, 0.2° rotation step; Bruker Corporation,  
94 Billerica, MA, USA).  $\mu$ -CT projection images were reconstructed to produce orthogonal slices  
95 with NRecon (v.1.6.9.18, Bruker Corporation, Billerica, MA, USA). For 3D segmentation of  
96 tracheae, the orthogonal slice data were imported into Amira-Aviso 6.7 (Thermo Fisher  
97 Scientific, Waltham, Massachusetts, USA), and the lumen of the tracheae was selected using  
98 the magic wand tool every 5 slices throughout the whole dataset, followed by interpolation to  
99 connect slices. This selection was then used to generate a 3D surface and 2D image. The 3D  
100 image of the inner ear of the katydid (*Mimetica* sp.) is modified from Celiker et al<sup>101</sup>.

101

## 102 **Gaussian process regression for predicting syllable rates in fossilised insects**

103 This study employed a machine learning approach to estimate the syllable rates of calling song  
104 of extinct orthopteran insects based on preserved the morphological and the simulated acoustic  
105 traits. Gaussian Process Regression (GPR) was selected as the core modelling technique due to  
106 its non-parametric, probabilistic framework, as it does not impose a fixed functional form on  
107 the data. GPR is well-suited to small-to-medium-sized biological datasets, making it  
108 appropriate for the limited number of extant species available for training<sup>102</sup>. Additionally, it  
109 enables the generation of confidence intervals alongside point predictions, allowing  
110 quantification of uncertainty, an important requirement when extrapolating to fossil taxa. The  
111 ability of the model to capture non-linear relationships while extrapolating to regions beyond  
112 the training data make GPR particularly effective for reconstructing extinct calling song.

### 113 **Training Dataset and Features**

114 The training dataset was compiled on four input features based on the morphological and the  
115 acoustic traits of extant and extinct species:

- 116 1. The stridulatory file length (mm)
- 117 2. Total number of teeth on the stridulatory file
- 118 3. The dominant frequency (kHz) of the species' acoustic signa
- 119 4. The syllable duration (ms) in the call.

120 The target variable was the syllable rate, calculated from the equation of  
121 'syllable/wingstroke/phantome rate changes with temperature' from existing literatures

122 (Supplementary Table 4)<sup>103–111</sup>. An ambient temperature of 20 °C was selected for the syllable-  
123 rate calculations as it sits near the centre of Jurassic climate estimates from multiple lines of  
124 evidence. Global multi-proxy compilations place mean surface values between ~19.6 °C (Early-  
125 Jurassic cool interval) and ~24.6 °C (Toarcian warm interval)<sup>112</sup>; high-latitude TEX-86 records  
126 from the Falkland Plateau yield consistently warm sea-surface temperatures of 26–30 °C during  
127 the Middle-to-Late Jurassic<sup>113</sup>; and a mid-latitude continental reconstruction for the Callovian  
128 Yanliao Biota indicates mean annual air temperatures of 15–20 °C<sup>114</sup>. A value of 20 °C  
129 therefore provides a representative midpoint for the range of Jurassic ambient conditions. Some  
130 species exhibited two distinct syllable rate–temperature equations, from which the higher  
131 syllable rate was selected for modelling to ensure a consistent and conservative estimate of the  
132 species’ maximum acoustic performance. This approach establishes an upper bound for  
133 communication rate based on available data and avoids underestimating the insect’s potential  
134 signalling capacity. Species with complex phonotomes (calling song consisting of multiple  
135 syllable and different syllable rate equation for different syllables) were ignored to reduce  
136 complexity of the model for prediction.

### 137 **Kernel Construction**

138 The GPR model's behaviour is governed by its kernel (covariance function), which defines  
139 similarity between data points. A composite kernel was constructed:

$$140 \quad k(x, x') = c_1 \cdot \text{Matern}_\nu(\ell) + c_2 \cdot \text{DotProduct} + \text{WhiteKernel}$$

- 141 • The Matérn kernel  $\text{Matern}_\nu(\ell)$  was used for modelling spatial smoothness, where  $\ell$  is  
142 the characteristic length scale and  $\nu \in \{0.5, 1.5, 2.5\}$  controls smoothness (from rough to  
143 smooth functions). The scaling constant  $c_1$  modulates the variance of the function prior,  
144 essentially controlling how much influence the Matérn component has on the output.  
145 Larger values of  $c_1$  allow the model to capture higher variability driven by smooth  
146 patterns in the input space. This kernel was chosen to capture local non-linearities while  
147 providing a tuneable smoothness prior, which has been effective in ecological and  
148 evolutionary models.
- 149 • The DotProduct kernel, scaled by  $c_2$ , captures linear relationships and supports  
150 extrapolation, which is critical when making predictions for fossil data lying outside the  
151 range of the extant species. The scaling constant  $c_2$  defines how much weight this linear  
152 trend contributes to the overall model.

- 153       • A WhiteKernel captures small observational noise, allowing for non-zero variance even  
154       when inputs are identical and avoid overfitting.

155 Together,  $c_1$  and  $c_2$  balance the contributions of the Matérn and linear components of the  
156 model. This hybrid structure enhances the model's flexibility as it can fit nonlinear trends within  
157 the range of known species, while still being capable of generalising linearly the unseen,  
158 extrapolated fossil inputs.

### 159 **Log-Transformation of the Target**

160 Since syllable rate values must be positive and spanned an order of magnitude, the target  
161 syllable rate was transformed as:

$$162 \quad y_{log} = \log(y)$$

163 This transformation improves normality, variance stability, and ensures that predicted rates  
164 remain positive. After prediction, values were exponentiated:

$$165 \quad \hat{y} = \exp(\mu \pm \sigma)$$

166 where  $\mu$  is the mean predicted log-rate and  $\sigma$  is the standard deviation from the GPR posterior.

### 167 **Hyperparameter Tuning via Bayesian Optimisation**

168 Kernel hyperparameters, including  $\ell, \nu, \sigma_0, c_1, c_2$  and noise level were optimised using  
169 Bayesian optimisation via the Optuna framework to efficiently explore complex, non-convex  
170 hyperparameter spaces<sup>115</sup>. The objective function was defined as the negative mean squared  
171 error (MSE) over 3-fold cross-validation:

$$172 \quad MSE = \frac{1}{n} \sum_{i=1}^n (y_i - \hat{y}_i)^2$$

173 The search for the parameters was terminated after 1000 trials or earlier if the best value did  
174 not improve for 200 consecutive iterations.

### 175 **Model Evaluation**

176 After training, model performance was evaluated on the full dataset using three metrics:

- 177       • Mean Absolute Error (MAE):

178 
$$MAE = \frac{1}{n} \sum_{i=1}^n |y_i - \hat{y}_i|$$

179 Measures average absolute deviation, reflecting typical error magnitude.

- 180 • Root Mean Squared Error (RMSE):

181 
$$RMSE = \sqrt{\frac{1}{n} \sum_{i=1}^n (y_i - \hat{y}_i)^2}$$

182 Emphasises larger errors due to squaring, useful for detecting outlier influence.

- 183 • Coefficient of Determination ( $R^2$ ):

184 
$$R^2 = 1 - \frac{\sum (y_i - \hat{y}_i)^2}{\sum (y_i - \bar{y})^2}$$

185 Represents the proportion of variance explained by the model. Values near 1 indicate high  
186 predictive accuracy.

187 All metrics were additionally normalised by the mean syllable rate to express relative  
188 performance.

### 189 **Optimal hyper parameter**

190 Following Bayesian optimisation, the Gaussian Process Regression model converged on the  
191 following kernel hyperparameters as optimal for predicting log-transformed syllable rates:  $c_1 =$   
192  $1.23$ ,  $\ell = 1.46$ ,  $\nu = 1.5$ ,  $c_2 = 0.731$ ,  $\sigma_0 = 0.136$ , and *noise level* =  $5.95 \times 10^{-5}$ . These  
193 values were used to construct the final kernel and train the model on the complete dataset.

### 194 **Application to Fossil Data**

195 The validated GPR model was applied to predict syllable rates in the fossil taxa. Each fossil  
196 species was represented by a vector of four inputs: stridulatory file length, tooth count,  
197 estimated calling frequency, and the estimated syllable duration. GPR outputs were converted  
198 from log space and plotted with standard deviation error bars to reflect prediction uncertainty.

199 For each fossil, the maximum possible rate was calculated to compare predicted values with  
200 the theoretical bound to ensure biological plausibility:

201 
$$\text{Max syllable rate} = \frac{1000}{\text{Syllable duration (ms)}}$$

202 **Model limitation**

203 While GPR provides a powerful probabilistic framework for estimating syllable rates in extinct  
204 taxa, it is important to acknowledge the model's limitations in reconstructing full acoustic  
205 behaviours. The current model predicts syllable rate based on morphological and acoustic data  
206 under the assumption that these traits directly and consistently determine rhythmic sound  
207 production across taxa. However, this prediction represents only a single component of a more  
208 complex acoustic signal.

209 In particular, the model assumes that a species' call consists of simply regular, trill-like syllable  
210 production patterns. Real insect songs sometimes also include structured elements such as  
211 chirps, phrases, pauses, and modulations, shaped by neurophysiological controls,  
212 environmental pressures, and species-specific behavioural contexts which are not captured by  
213 morphological features alone. Finally, some fossils may fall outside the range of known species  
214 used to train the model and should be interpreted with caution.

215 Still, the model's predicted syllable rates serve as a biomechanical estimate of sound rhythm  
216 potential, useful primarily for reconstructing hypothetical trilling signals under idealised  
217 conditions rather than complete reconstructions of fossil sound.

218 **Results – GPR model performance and evaluation**

219 The trained Gaussian Process Regression (GPR) model demonstrated strong predictive  
220 performance when evaluated on the full dataset of extant insect species. The model was  
221 assessed using three standard regression metrics: mean absolute error (MAE), root mean  
222 squared error (RMSE), and the coefficient of determination ( $R^2$ ). Predictions were made on the  
223 log-transformed syllable rate, then exponentiated to yield values in the original scale  
224 (syllables/second).

225 The mean absolute error (MAE) was 2.42 syllables/sec, corresponding to approximately 5.5%  
226 of the mean syllable rate in the dataset. This indicates that, on average, the model's predictions  
227 deviate from the true syllable rate by just over 2 syllables per second—a small discrepancy  
228 considering that some species reach rates over 90 syllables/sec. The root mean squared error  
229 (RMSE) was 4.10 syllables/sec (9.4%), showing that the model maintains good robustness even

230 when occasional larger errors occur, and that extreme outliers are not a concern. The model  
231 achieved an  $R^2$  value of 0.966, indicating that 96.6% of the variance in the observed syllable  
232 rates is explained by the GPR model. This level of explanatory power is considered excellent  
233 in biological data modelling and suggests that the chosen features—file length, tooth count,  
234 carrier frequency, and syllable duration—collectively contain strong predictive signals for  
235 acoustic output.

236 Visual inspection of the actual vs predicted plot (see Extended Data, Fig 8b) confirms that  
237 majority of predicted values fall close to the identity line ( $y = x$ ), with no systematic over- or  
238 under-prediction across the range. Slight underestimation is observed for some of the highest  
239 syllable rates, which likely reflects the relatively lower representation of high-rate species in  
240 the training data and the conservative nature of GPR models when extrapolating near the  
241 boundaries of the input space.

242 Taken together, these results validate the use of Gaussian Process Regression for predicting  
243 insect syllable rates from morphological and acoustic features. The model's high accuracy, low  
244 error margins, and built-in uncertainty estimates make it well-suited for extrapolating to fossil  
245 specimens while maintaining biological plausibility.

## 246 **Results – Syllable rate prediction of fossilised insects**

247 Predicted syllable rates for the nine fossil insect species varied widely across taxa, with  
248 corresponding confidence intervals reflecting the degree of uncertainty in each estimate  
249 (Extended Data, Fig 8c). Most predictions fell well below their respective biomechanical  
250 limits, which were computed as the inverse of syllable duration and served as hard upper  
251 bounds on calling rate.

252 Predicted syllable rates for nine fossil insect species using Gaussian Process Regression. Blue  
253 markers indicate the mean predicted syllable rate for each species, with vertical error bars  
254 representing standard deviation. Red markers denote the maximum syllable rate for each  
255 species.

256 *Archaboilus polyneurus* showed a moderate predicted rate ( $33.72 \pm 9.64 \text{ s}^{-1}$ ), substantially  
257 below its theoretical maximum ( $90.91 \text{ s}^{-1}$ ), indicating biologically plausible calling behaviour.  
258 In contrast, *Aboilus stratosus* exhibited a lower predicted rate ( $8.39 \pm 2.42 \text{ s}^{-1}$ ), yet remained  
259 below its biomechanical ceiling ( $25.32 \text{ s}^{-1}$ ).

260 Some taxa exhibited particularly low predicted syllable rates, including *Allaboilus gigantus*  
261 ( $0.63 \pm 1.08 \text{ s}^{-1}$ ) and *Aboilinae sp. 1* ( $3.26 \pm 2.50 \text{ s}^{-1}$ ), likely due to long syllable durations.  
262 These predictions, while conservative, were accompanied by relatively small standard  
263 deviations, indicating higher model confidence in the low estimates.

264 Other species such as *Sigmaboilus peregrinus* ( $41.38 \pm 32.71 \text{ s}^{-1}$ ) and *Novaboilus ovatus*  
265 ( $28.78 \pm 13.52 \text{ s}^{-1}$ ) showed wide predictive intervals, suggesting greater extrapolation  
266 uncertainty due to feature combinations not well represented in the extant training data.  
267 Nevertheless, their mean values remained comfortably below their duration-based limits  
268 ( $133.33$  and  $62.50 \text{ s}^{-1}$ , respectively), upholding biological plausibility.

269 Across all species, predicted syllable rates remained below their corresponding physical  
270 maxima, and the distribution of values reflected both anatomical potential and statistical  
271 uncertainty.

## 272 **Supplementary discussion**

### 273 **Notes on the FEA method**

274 While we lack sufficient data of wing thickness across enough extant taxa to improve the  
275 method at this stage, we emphasise that this model was used only to recover the vibrational  
276 decay of the wing in response to stimulation in the time domain studies. It also allows for  
277 simpler modelling approaches to reduce computation times. The disadvantage is that if some  
278 species have unique membrane or vein thicknesses within the vibration region that modify the  
279 wing vibration, these are not captured in the model<sup>116</sup>.

### 280 **Relic condition of tegminal stridulation**

281 The relic condition for wing stridulation appears to have started with wings developing  
282 sclerotised pegs, randomly distributed on special wing veins, as observed in some  
283 cockroaches<sup>117</sup>, Mantids<sup>118</sup>, in some living Tettigoniidae (e.g. *Pholidoptera* spp.<sup>119</sup>), and in the  
284 living Prophalangopsidae, which have traces of vestigial networks of wing veins that exhibit  
285 non-functional stridulatory teeth (see Extended Data Fig. 8). Random files struck at the time  
286 would produce only broadband calls, as observed in females of many living Tettigoniidae  
287 species, which evolved multiple stridulatory veins for duet acoustic response (e.g. many  
288 Phaneropterinae species<sup>5</sup>, and in Pseudophyllinae, e.g. *Panoploscelis* spp.<sup>120</sup>). The evolution

289 of a single stridulatory file, with systematically arranged teeth, is a clear departure or  
290 improvement from the relic condition of stridulation.

### 291 **Wing symmetry and stridulation**

292 Most male Tettigoniidae have asymmetric wings, and have adopted left-over right-wing  
293 position, with the left wing bearing the active file, and the right wing the active plectrum. Yet,  
294 the earliest Tettigoniidae diverging lineage, the Nedubini, which exhibit symmetric wings, is  
295 ambidexterous<sup>121</sup>, just like grigs (see below). On the other hand, males of Prophalangopsidae  
296 (the grigs, a relic family closely related to modern-day katydids), use symmetric wings and can  
297 switch wing overlap during stridulation, just like the earliest diverging Tettigoniidae lineage.  
298 Producing pure-tone low frequencies <10 kHz, requires two wings (or two speakers) oscillating  
299 in phase to maximise sound output and intensity<sup>122</sup>, and this is well studied in field crickets,  
300 which use pure tones at ca 5 kHz. The grig *Tarragilus diuturnus* uses similar frequencies, and  
301 to the human ear, their calls sound exactly like those of field crickets (Extended Data, Fig. 1).  
302 This suggests these species, and their extinct ancestors singing at frequencies below 10 kHz<sup>123</sup>,  
303 used a wing coupling mechanism (like the field cricket escapement) to synchronise both wings  
304 in vibration, and avoid destructive interference to maintain a pure-tone signal<sup>122</sup>. Indication of  
305 this symmetrical mechanism could be identified in fossilised wings even if only one wing is  
306 found (see Extended Data Figs. 5-6). For example, a single wing with a fully developed file and  
307 a fully developed plectrum (designed to scrape a functional file in the opposite wing), suggests  
308 that its counterpart likely had the same structures (symmetry) for ambidextrous stridulation.

### 309 **Bimodal temporal/frequency modulation**

310 A single wing closing phase produces the most basic oscillation of the call, termed here a  
311 'syllable' (Extended Data, Video1). Syllables can be grouped or delivered in sequence to form  
312 a repertoire, which includes variations in time and frequency as the main parameters for specific  
313 recognition.

314 In many extant species, a systematic file-tooth distribution can affect the instantaneous  
315 frequency and amplitude components of the syllable. This has been described as mechanical  
316 frequency modulation (FM) and has been observed in the calls of the leaf mimicking katydids  
317 Pterochrozini<sup>124</sup>. This seems to be also a mechanism adopted by some Jurassic Ensifera like *A.*  
318 *polyneurus* (see Extended data, Fig. 7).

## 319 **Insect ear evolution**

320 Insect ears arise from the specialisation of pre-existing mechanoreceptor organs (precursor  
321 organs) that detect substrate vibrations into organs that detect airborne sound<sup>125</sup>. Convincing  
322 support for a vibratory origin of the auditory system is given by many interneurons with  
323 bimodal vibratory and auditory response properties<sup>126</sup>. Therefore, the ability to detect airborne  
324 sounds seems to be an evolutionary addition to the pre-existing adaptation<sup>127</sup>. Importantly, the  
325 auditory sensilla precursor to the *cristica acustica* (CA) is found in the complex tibial  
326 scolopidial organ of atympanate Ensifera, where the sensilla are specialised in substrate  
327 vibration detection. Notable structural changes occurred during the transformation of  
328 scolopidial cells specialised in vibrations (low frequencies) to functional sound detectors.

329 A precursor scolopidium might have started being sensitive to high-amplitude sound before  
330 tympana and acoustic trachea appeared. A good example of this condition is preserved in the  
331 subgenual organ of some living cockroach species, and the high wing chordotonal organ of  
332 locust, both of which have been shown to respond to sound without any tympanal  
333 adaptation<sup>128,129</sup>. In this context, sound-capturing structures evolved in successive steps,  
334 transforming the cuticle into tympana, and a respiratory trachea into an air space to enhance  
335 tympanal vibrations. Subsequently, the tracheal air space backing the tympana was modified  
336 into an acoustic trachea or ear canal (Fig. 5a-c), which in modern katydid species focuses on  
337 capturing and conducting sounds to the tympanal organ. This gradual transition from vibrational  
338 to airborne hearing has been convergently followed in the mammalian transition from jaw bones  
339 to the formation of the middle ear ossicles<sup>130</sup>. The timing of this mammalian hearing transition  
340 coincides with the specialisation of insectivorous dentition, suggesting that eavesdropping on  
341 and predation of singing insects were likely among the driving forces of this transition<sup>131</sup>. The  
342 elongation of the cochlear canal to the cochlea of therian mammals was likely constrained and  
343 triggered by the coevolution between these small animals and their prey, acoustically active  
344 orthopterans<sup>132</sup>.

## 345 **Relic condition of the acoustic trachea**

346 A bifurcated auditory trachea seems to be the plesiomorphic condition of a functional acoustic  
347 trachea, as it also occurs in atympanate Ensifera (e.g., Gryllacrididae, see Extended data Fig.  
348 9ab), and is also observed in nymphs during the ontogenetic development of Tettigoniidae  
349 species.

350 Ears have evolved at least 19 times independently in insects. In the period before bats, ears and  
351 complex acoustical behaviours appeared independently in at least seven insect orders<sup>126,133,134</sup>.  
352 It was recently shown that at least four of the species-rich moth clades (Drepanoidea,  
353 Geometroidea, Noctuoidea, and Pyraloidea) evolved ears in the Late Cretaceous (some 103.4  
354 to 67 Ma), several million years before the echolocating bat<sup>135</sup>. The authors suggest that hearing  
355 organs in Lepidoptera, and in animals more broadly, evolved to provide auditory surveillance  
356 of the environment for broadband sounds produced by potential predators. Behavioural and  
357 neural evidence have shown that moths respond to the low-frequency (<20 kHz) walking and  
358 wingbeat sounds of predatory birds<sup>136,137</sup>. This suggests that the hearing organs of moths and  
359 other insects likely evolved first for auditory surveillance before subsequently being co-opted  
360 for bat detection.

361

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505 **Supplementary notes**

506

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537 **Competing Interests declaration**

538 The authors declare not competing interest.

539

540

541



```

543  MATLAB CODE FOR CALL RECONSTRUCTION BASED ON EXCITATION OF A FOSSILISED
544  WING RECOVERED IN 2D

545  %%%%%%%%%%%%%%% Syllable Generation
546  %%%%%%%%%%%%%%%

547  wav = readmatrix('COMSOL_vibration file.txt');

548  wavdt = detrend(wav(:,2));

549

550  %[b,a] = butter(9,3000/100000,'high');

551  %wavbut = filter(b,a,wav(:,2))

552

553  dt = readmatrix('DeltaT_vector.txt');

554  x = zeros(length(wav(:,2))+length(dt)*ceil(mean(dt*2e5)),1);

555  deltat = 0;

556  lastdt = 0;

557  x(1:length(wav(:,2))) = x(1:length(wav(:,2)));

558

559  for i = 1:length(dt)

560  lastdt = deltat;

561  deltat = deltat + round(dt(i)*1e5);

562  x(1+deltat:deltat+length(wav(:,2))) = x(1+deltat:deltat+length(wav(:,2))) + wavdt;

563  end

564

```

```

565 figure
566 plot(x)
567
568 %%%%%%%%%%%%%%% FFT
569 %%%%%%%%%%%%%%%
570
571 p=nextpow2(length(x)); %%%
572 Ln=2^(p-1);
573 fs=1/wav(2,1);
574 dt = 1/fs;
575 t = 0:dt:(Ln*dt)-dt;
576
577 f = x;
578
579 frq = (fs/Ln)*(0:Ln/2);
580 f = detrend(f);
581 fft_dat=fft(f(1:Ln)); %%%
582
583 fft_dat2=fft_dat;
584 threshold = max(abs(fft_dat)/Ln)/10000;
585 fft_dat2(abs(fft_dat)/Ln<threshold) = 0;
586

```

```
587 mag_dat = 2*abs(fft_dat(1:Ln/2+1)/Ln);
588 phase_dat = unwrap(angle(fft_dat2(1:Ln/2+1)/Ln));
589
590 figure
591 %subplot(2,1,1)
592 plot(freq(50:4096)/1000,mag_dat(50:4096),'r','LineWidth',1.5)
593 xlabel('Frequency (kHz)')
594 ylabel('Magnitude (Pa)')
595 title('Frequency Decomposition')
596 %axis([0 64 0 110])
597 grid on
598
599
600
```