

1                   **Virtual prototyping of non-invasive spinal cord electrical stimulation**  
2                                   **targeting upper limb motor function**  
3                                   **Supplementary Information**

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5 Abdallah Alashqar<sup>1,2</sup>, Nabila Brihmat<sup>3</sup>, Vincent Gemar<sup>1,2</sup>, Zhaoshun Hu<sup>1,2</sup>, Seong-Ryong Koh<sup>4</sup>,  
6 Sandra Diaz-Pier<sup>5</sup>, Roberto de Freitas<sup>6,7,8</sup>, Atsushi Sasaki<sup>9</sup>, Matija Milosevic<sup>6,10,11,12</sup>, Rodolfo  
7 Keeseey<sup>13,14</sup>, Ismael Seáñez<sup>13,14,15,16</sup>, Esra Neufeld<sup>17</sup>, H el ene Cassoudehalle<sup>18</sup>, Ursula  
8 Hofstoetter<sup>19</sup>, Karen Minassian<sup>19</sup>, Fabien Wagner<sup>3</sup>, Andreas Rowald<sup>1,2</sup>

9  
10 <sup>1</sup> Department of Medical Informatics, Biometry and Epidemiology, Friedrich-Alexander-  
11 Universit at Erlangen-N urnberg, Erlangen 91052, Germany

12 <sup>2</sup> Department of Artificial Intelligence in Biomedical Engineering, Friedrich-Alexander-  
13 Universit at Erlangen-N urnberg, Erlangen 91052, Germany

14 <sup>3</sup> Univ. Bordeaux, CNRS, IMN, UMR 5293, F-33000 Bordeaux, France

15 <sup>4</sup> Simulation and Data Lab Highly Scalable Fluids & Solids Engineering, J ulich Supercomputing  
16 Ctr. (JSC), Institute for Advanced Simulation, Forschungszentrum J ulich GmbH, 52428 J ulich,  
17 Germany

18 <sup>5</sup> Simulation and Data Lab Neuroscience, J ulich Supercomputing Ctr. (JSC), Institute for  
19 Advanced Simulation, Forschungszentrum J ulich GmbH, 52428 J ulich, Germany

20 <sup>6</sup> Department of Mechanical Science and Bioengineering, Graduate School of Engineering  
21 Science, Osaka University, Toyonaka, Japan

22 <sup>7</sup> Rehab Neural Engineering Labs, University of Pittsburgh, Pittsburgh, PA 15219, USA

23 <sup>8</sup> Department of Neurological Surgery, University of Pittsburgh, Pittsburgh, PA 15260, USA

24 <sup>9</sup> Department of Life Sciences, Graduate School of Arts and Sciences, The University of Tokyo,  
25 Meguro-ku, Tokyo 153-8902, Japan

26 <sup>10</sup> The Miami Project to Cure Paralysis, Miller School of Medicine, University of Miami, Miami,  
27 FL 33136, USA

28 <sup>11</sup> Department of Neurological Surgery, Miller School of Medicine, University of Miami, Miami,  
29 FL 33136, USA

30 <sup>12</sup> Department of Biomedical Engineering, University of Miami, FL 33146, USA

31 <sup>13</sup> Department of Biomedical Engineering, Washington University in St. Louis, St. Louis, MO  
32 63105, USA

33 <sup>14</sup> Division of Neurotechnology, School of Medicine, Washington University in St. Louis, MO  
34 63110, USA

35 <sup>15</sup> Department of Neurosurgery, School of Medicine, Washington University in St. Louis, MO  
36 63110, USA

37 <sup>16</sup> Preston M. Green Department of Electrical and Systems Engineering, Washington  
38 University in St. Louis, MO 63130, USA

39 <sup>17</sup> Foundation for Research on Information Technologies in Society (IT'IS), Z urich 8004,  
40 Switzerland

41 <sup>18</sup> Department of Physical Medicine and Rehabilitation, CHU de Bordeaux, F-33000 Bordeaux,  
42 France

43 <sup>19</sup> Center for Medical Physics and Biomedical Engineering, Medical University of Vienna,  
44 Vienna 1090, Austria

45  
46 **Corresponding author:**

47 **Andreas Rowald, PhD**

48 Friedrich-Alexander-Universit at Erlangen-N urnberg

49 [andreas.rowald@fau.de](mailto:andreas.rowald@fau.de)

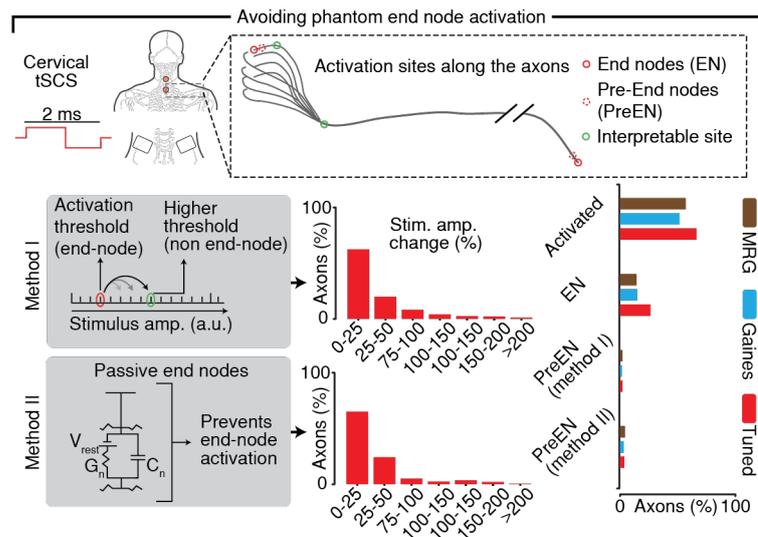
50 **Supplementary methods:**

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52 **End-nodal recruitment:**

53 We noticed a phenomenon of end-nodal recruitment for some axons, a known limitation  
54 of conductance-based compartmental cable models<sup>3,4</sup>. To ensure the interpretability of our  
55 simulation results, we sought to avoid such activations. Therefore, we introduced two methods  
56 of avoiding phantom end-node activations and assessed their ability in shifting the initiation  
57 site of action potentials (ISAPs), in addition to their effect on the threshold of activation  
58 (**Supplementary Fig. 1**). Based on our results, we replaced terminal nodes with passive nodes  
59 to avoid end-node recruitment<sup>3</sup> (**Supplementary Fig. 1**).

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62 **Supplementary Fig. 1.** Proposed methods for avoiding non-interpretable end-node activations  
63 observed in simulations of extracellularly stimulating conductance-based compartmental cable  
64 models<sup>3,4</sup>. Top: electrode configuration where end-nodes activations could occur and end-  
65 nodes highlighted along a sketch of nerve axons. Bottom: Proposed methods for avoiding  
66 phantom end-node activations. Method I: Avoiding end-node activation by increasing stimulus  
67 amplitude until a new activation site is present. Method II: Avoiding end-node activation by  
68 replacing the nodes of Ranvier at the termini with passive nodes<sup>3</sup>, preventing any activation to  
69 be initiated from them. The red bar plots show histograms of the relative stimulus threshold  
70 changes caused by using each of the methods on the tuned cable model, while the vertical bar  
71 chart shows the percentage of axons exhibiting end-node activation as well as the percentage  
72 of axons where the activation moved to only the next node after applying each of the two  
73 methods using each of the three different cable models. Abbreviations: millisecond (ms), end  
74 nodes (EN), pre-end nodes (PreEN), nodal conductance ( $G_n$ ), nodal capacitance ( $C_n$ ), resting  
75 membrane potential ( $V_{rest}$ ).

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77 **Axon model tuning:**

78 As mentioned in the methods' subsection "Axon model tuning", we constructed a  
79 parameter space composed of all parameters, for which we found reported variations<sup>5-14</sup> of ion  
80 channel properties between somatosensory afferents and motor efferents (**Supplementary**  
81 **Table 4**). We ensured that all sampled parameter combinations preserved the reported  
82 property differences<sup>5-14</sup> (**Supplementary Table 4**).

Segment	Reported avg. segment length <sup>1</sup> (mm)	Reported avg. REZ length <sup>1</sup> (mm)	Reported avg. segment length percentage <sup>2</sup> (%)	Calculated segment length (mm)	Calculated ratio (avg. REZ length / avg. segment length)	Calculated REZ length (mm)
<b>C1</b>	12.60*	11.30*	1.60	7.57	0.90	6.79
<b>C2</b>	12.60	11.30	2.20	10.41	0.90	9.34
<b>C3</b>	13.30	9.40	3.50	16.57	0.71	11.71
<b>C4</b>	13.90	11.60	3.50	16.57	0.83	13.83
<b>C5</b>	15.00	12.40	3.50	16.57	0.83	13.70
<b>C6</b>	13.60	11.50	3.30	15.62	0.85	13.21
<b>C7</b>	11.70	11.40	3.20	15.15	0.97	14.76
<b>C8</b>	12.50	11.80	3.40	16.09	0.94	15.19
<b>T1</b>	13.00	12.00	3.60	17.04	0.92	15.73
<b>T2</b>	16.40	13.10	3.90	18.46	0.80	14.75
<b>T3</b>	16.10	15.30	4.40	20.83	0.95	19.79
<b>T4</b>	22.80	18.40	5.00	23.67	0.81	19.10
<b>T5</b>	22.10	19.60	5.10	24.14	0.89	21.41
<b>T6</b>	24.80	18.80	5.60	26.51	0.76	20.09
<b>T7</b>	24.50	20.10	5.60	26.51	0.82	21.75
<b>T8</b>	25.50	19.00	5.40	25.56	0.75	19.04
<b>T9</b>	23.90	20.40	5.10	24.14	0.85	20.60
<b>T10</b>	25.30	19.30	4.70	22.25	0.76	16.97
<b>T11</b>	22.40	15.50	4.30	20.35	0.69	14.08
<b>T12</b>	18.40	15.60	3.90	18.46	0.85	15.65
<b>L1</b>	17.50	15.20	3.60	17.04	0.87	14.80
<b>L2</b>	14.00	11.80	2.80	13.25	0.84	11.17
<b>L3</b>	11.20	11.20	2.40	11.36	1.00	11.36
<b>L4</b>	12.50	11.60	2.20	10.41	0.93	9.66
<b>L5</b>	9.70	11.20	1.70	8.05	1.15	9.29
<b>S1</b>	9.70*	11.20*	1.50	7.10	1.15	8.20
<b>S2</b>	9.70*	11.20*	1.60	7.57	1.15	8.74
<b>S3</b>	9.70*	11.20*	1.40	6.63	1.15	7.65
<b>S4</b>	9.70*	11.20*	1.30	6.15	1.15	7.10

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86 **Supplementary Table 1.** Reported<sup>1</sup> and calculated segment-specific morphometric  
87 parameters used for the 3D rootlets model generation. \*These parameters were not reported  
88 in the referenced publication but were extrapolated from parameters of the closest reported  
89 segments. Abbreviations: average (avg.), millimeter (mm), root entry zone (REZ).

Segment	Reported avg. number of rootlets <sup>1</sup>		Calculated number of rootlets		Reported avg. root diameter <sup>1</sup> (mm)		Calculated rootlet diameter (mm)	
	P	A	P	A	P	A	P	A
<b>C1</b>	8.33*	8.33*	5	5	4.34*	2.79*	0.87	0.56
<b>C2</b>	8.33	8.33	7	7	4.34	2.79	0.62	0.40
<b>C3</b>	8.25	6.25	11	8	4.55	2.63	0.41	0.33
<b>C4</b>	8.87	7.62	11	9	4.84	2.85	0.44	0.32
<b>C5</b>	9.22	8.14	10	9	5.43	3.78	0.54	0.42
<b>C6</b>	8.77	6.85	10	8	5.08	3.29	0.51	0.41
<b>C7</b>	7.77	7.25	10	9	5.50	2.92	0.55	0.32
<b>C8</b>	7.66	6.62	10	9	5.18	2.19	0.52	0.24
<b>T1</b>	6.00	4.66	8	6	3.85	1.80	0.48	0.30
<b>T2</b>	5.00	4.33	6	5	3.35	1.82	0.56	0.36
<b>T3</b>	4.88	4.22	6	6	3.37	1.33	0.56	0.22
<b>T4</b>	4.44	4.33	5	4	3.21	1.38	0.64	0.34
<b>T5</b>	4.00	4.88	4	5	3.29	1.47	0.82	0.29
<b>T6</b>	4.55	4.44	5	5	3.62	1.71	0.72	0.34
<b>T7</b>	4.22	4.66	5	5	3.27	1.71	0.65	0.34
<b>T8</b>	4.55	4.66	5	5	3.73	1.64	0.75	0.33
<b>T9</b>	5.44	4.66	6	5	3.83	1.43	0.64	0.29
<b>T10</b>	4.88	4.55	4	4	3.71	1.67	0.93	0.42
<b>T11</b>	5.33	3.88	5	4	3.20	1.32	0.64	0.33
<b>T12</b>	6.22	4.11	6	4	3.53	1.47	0.59	0.37
<b>L1</b>	7.22	5.33	7	5	3.84	2.45	0.55	0.49
<b>L2</b>	8.00	5.88	8	6	4.60	2.94	0.57	0.49
<b>L3</b>	8.55	6.33	8	6	4.26	2.70	0.53	0.45
<b>L4</b>	7.55	5.00	6	4	4.40	3.19	0.73	0.80
<b>L5</b>	8.22	5.33	7	5	4.98	2.83	0.71	0.57
<b>S1</b>	8.22*	5.33*	6	4	4.98*	2.83*	0.83	0.71
<b>S2</b>	8.22*	5.33*	7	4	4.98*	2.83*	0.71	0.71
<b>S3</b>	8.22*	5.33*	5	3	4.98*	2.83*	1.00	0.94
<b>S4</b>	8.22*	5.33*	5	3	4.98*	2.83*	1.00	0.94

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92 **Supplementary Table 2.** Reported<sup>1</sup> and calculated segment- and position-specific  
93 morphometric parameters used for the 3D rootlets model generation. \*These parameters were  
94 not reported in the referenced publication but were extrapolated from parameters of the closest  
95 reported segments. Abbreviations: average (avg.), millimeter (mm), posterior (P), anterior (A)

Root pairs	Left		Right	
	Reported occurrences <sup>1</sup> (n=9)	Modelled	Reported occurrences <sup>1</sup> (n=9)	Modelled
C2-C3	7	✓	4	X
C3-C4	9	✓	6	✓
C4-C5	6	✓	4	X
C5-C6	7	✓	7	✓
C6-C7	7	✓	5	✓
C7-C8	6	✓	5	✓
C8-T1	2	X	2	X
L1-L2	2	X	1	X
L2-L3	0	X	0	X
L3-L4	2	X	1	X
L4-L5	1	X	0	X
L-S1	1	X	0	X

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**Supplementary Table 3.** Reported occurrences of inter-root anastomoses<sup>1</sup> and their inclusion in the modeling of the 3D structures in our model. Only anastomoses with occurrences 5 or more occurrences (>50%) were considered in the modeling.

Tissue	Maximum step (X, Y, Z in mm)	Geometry resolution (X, Y, Z in mm)
Rootlets	0.22, 0.22, 0.22	0.18, 0.18, 0.18
Peripheral nerves	2.0, 2.0, 2.0	1.0, 1.0, 1.0
Cranial nerve branches (including vagus nerve)	2.0, 2.0, 2.0	1.45, 1.45, 1.45
Gray matter, white matter (SC), cerebrospinal fluid and dura mater	1.0, 1.0, 2.0	1.0, 1.0, 1.0
Skin	0.5, 0.5, 1.0	0.5, 0.5, 1.0
Tissue hole filler	3.0, 3.0, 5.0	3.0, 3.0, 10.0
Other tissues	2.0, 2.0, 10.0	2.0, 2.0, 2.0

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**Supplementary Table 4.** Voxelization parameters used for the different tissues in the 3D whole-body model. Abbreviations: millimeter (mm), spinal cord (SC).

Ion channel property	Sensory / motor difference
Persistent sodium conductance ( $gNa_p$ )	Sensory > motor <sup>5-7</sup>
Slow potassium conductance ( $gK_s$ )	Sensory > motor (ratio = 1.55) <sup>8,9</sup>
Fast potassium conductance ( $gK_f$ )	Sensory < motor (ratio = 0.6) <sup>10</sup>
Leakage conductance ( $gL$ )	Sensory > motor (ratio = 1.5) <sup>11</sup>
Persistent sodium speed ( $\alpha m_p A$ , $\beta m_p A$ )	Sensory < motor <sup>12</sup>
Fast sodium speed ( $\alpha m A$ , $\beta m A$ )	Sensory < motor <sup>12</sup>
Sodium inactivation speed ( $\alpha h A$ , $\beta h A$ )	Sensory > motor <sup>8,12</sup>
Slow potassium speed ( $\alpha s A$ , $\beta s A$ )	Sensory > motor <sup>13</sup>
Slow potassium half-activation voltage ( $\alpha s B$ , $\beta s B$ )	Sensory < motor <sup>10,14</sup>
Fast potassium speed ( $\alpha n A$ , $\beta n A$ )	Sensory > motor <sup>13</sup>

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**Supplementary Table 5.** Ion channel differences between sensory and motor nerve fibers as reported in the literature across different species.  $\alpha$  parameters refer to opening of ion channels, while  $\beta$  parameters refer to closing of ion channels.

	Node			FLUT			MYSA, STIN
Voltage and time dependent parameters	A(ms <sup>-1</sup> )	B(mV)	C(mV)	A(ms <sup>-1</sup> )	B(mV)	C(mV)	
$\alpha_m$	1.86	21.4	10.3	-	-	-	-
$\beta_m$	0.086	25.7	9.16	-	-	-	-
$\alpha_{mp}$	0.01	27	10.2	-	-	-	-
$\beta_{mp}$	0.00025	34	10	-	-	-	-
$\alpha_h$	<b>0.0728</b>	114.0	11.0	-	-	-	-
$\beta_h$	2.3	31.8	13.4	-	-	-	-
$\alpha_n$	-	-	-	0.0462	-83.2	1.1	-
$\beta_n$	-	-	-	0.0824	<b>-60.8684</b>	10.5	-
$\alpha_s$	0.3	-27**	-5	-	-	-	-
$\beta_s$	<b>0.048</b>	10	-1	-	-	-	-
Channel Conductances	(mS cm <sup>-2</sup> )			(mS cm <sup>-2</sup> )			(mS cm <sup>-2</sup> )
Persistent Sodium	10			-			-
Fast Sodium	3000			-			-
Slow Potassium	80			-			-
Fast Potassium	-			20			-
Leak	7			-			-
Passive	-			0.1*			1 (MYSA), 0.1 (STIN)*
Reversal Potentials	(mV)			(mV)			
Sodium	50			-			-
Slow Potassium	-90.0			-			-
Fast Potassium	-			-90.0			-
Leak	-90.0			-			-
Resting potential (mV)	-78.05						

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111 **Supplementary Table 6.** Parameters used in the newly-tuned MRG-type model for  
112 somatosensory afferent axons. Highlighted are values that deviated from those reported in the  
113 original MRG-model<sup>8</sup>. \*This parameter scales with the ratio of segment diameter to fiber  
114 diameter as in the original MRG-model<sup>8</sup>. \*\*To avoid spontaneous activation, this parameter  
115 was modified for very small fibers (diameter < 5.16 $\mu$ m) but maintained sensory/motor  
116 difference (23 mV). Abbreviations: fluted (FLUT), stereotyped Internode (STIN), myelin sheath  
117 attachment (MYSA), ion channel conductance (g), ion channel opening rate ( $\alpha$ ), ion channel  
118 closing rate ( $\beta$ ), ion channel maximum speed of transition (A), ion channel half-activation  
119 voltage (B), ion channel response slope (C), sodium activation (m), persistent sodium  
120 activation (mp), sodium inactivation (h), fast potassium activation (n), slow potassium  
121 activation (s), millisecond (ms), millivolt (mV), milli Siemens (mS), centimeter (cm)

	Node			FLUT			MYSA, STIN
Voltage and time dependent parameters	A(ms <sup>-1</sup> )	B(mV)	C(mV)	A(ms <sup>-1</sup> )	B(mV)	C(mV)	
αm	<b>1.95789</b>	21.4	10.3	-	-	-	-
βm	<b>0.090526</b>	25.7	9.16	-	-	-	-
αmp	<b>0.016</b>	27	10.2	-	-	-	-
βmp	<b>0.00036959</b>	34	10	-	-	-	-
αh	<b>0.0728</b>	114.0	11.0	-	-	-	-
βh	<b>2.1789</b>	31.8	13.4	-	-	-	-
αn	-	-	-	<b>0.037149</b>	-83.2	1.1	-
βn	-	-	-	<b>0.0515</b>	-66	10.5	-
αs	0.3	-27	-5	-	-	-	-
βs	0.03	10	-1	-	-	-	-
Channel Conductances	(mS cm <sup>-2</sup> )			(mS cm <sup>-2</sup> )			(mS cm <sup>-2</sup> )
Persistent Sodium	10			-			-
Fast Sodium	3000			-			-
Slow Potassium	80			-			-
Fast Potassium	-			20			-
Leak	7			-			-
Passive	-			0.1*			1 (MYSA), 0.1 (STIN)*
Reversal Potentials	(mV)			(mV)			
Sodium	50			-			-
Slow Potassium	-90.0			-			-
Fast Potassium	-			-90.0			-
Leak	-90.0			-			-
Resting potential (mV)	-79.5						

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**Supplementary Table 7.** Parameters used in the tuned MRG-type model for motor efferent axons<sup>8</sup>. Highlighted are values that deviated from those reported in the original MRG-model. \*This parameter scales with the ratio of node diameter to fiber diameter as in the original MRG-model<sup>8</sup>. Abbreviations: fluted (FLUT), stereotyped Internode (STIN), myelin sheath attachment (MYSA), ion channel conductance (g), ion channel opening rate ( $\alpha$ ), ion channel closing rate ( $\beta$ ), ion channel maximum speed of transition (A), ion channel half-activation voltage (B), ion channel response slope (C), sodium activation (m), persistent sodium activation (mp), sodium inactivation (h), fast potassium activation (n), slow potassium activation (s), millisecond (ms), millivolt (mV), milli Siemens (mS), centimeter (cm)

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