

Table 1: Definitions and Formulas for Extracted Kinematic Features

Feature	Description	Equation / Definition
Grip Count	Number of grips completed during the task	$N_{\text{grips}} = \text{number of local maxima in the angle } \theta(t)$
Mean Grip Interval	Average time between grips	$\bar{T} = \frac{1}{N-1} \sum_{i=1}^{N-1} (t_{i+1} - t_i)$
SD Grip Interval	Variability in time between grips	$\sigma_T = \sqrt{\frac{1}{N-2} \sum_{i=1}^{N-1} ((t_{i+1} - t_i) - \bar{T})^2}$
Grip Frequency	Number of grips per second	$f = \frac{1}{\bar{T}}$
Opening and Closing Time	Fraction of task spent opening or closing hand	$T_{\text{open}} = \frac{\sum t_{\text{open}}}{T_{\text{total}}}, \quad T_{\text{close}} = \frac{\sum t_{\text{close}}}{T_{\text{total}}}$
Avg Opening and Closing Duration	Mean duration per opening/closing cycle	$\bar{t}_{\text{open}} = \frac{1}{N_{\text{open}}} \sum t_{\text{open}}, \quad \bar{t}_{\text{close}} = \frac{1}{N_{\text{close}}} \sum t_{\text{close}}$
Maximum Angular Amplitude	Max joint angle range (deg)	$A_{\text{max}} = \max(\theta(t)) - \min(\theta(t))$
Total Angular Rotation	Sum of absolute angle changes	$R = \sum_{i=1}^{N-1} \theta(t_{i+1}) - \theta(t_i) $
Mean Peak Angle	Average of local maxima in angle signal	$\bar{\theta}_{\text{peak}} = \frac{1}{N_p} \sum_{i=1}^{N_p} \theta(t_{p_i})$
SD of Peak Angle	Standard deviation of peak angles	$\sigma_{\text{peak}} = \sqrt{\frac{1}{N_p-1} \sum (\theta(t_{p_i}) - \bar{\theta}_{\text{peak}})^2}$
Mean Trough Angle	Average of local minima in angle signal	$\bar{\theta}_{\text{trough}} = \frac{1}{N_t} \sum_{j=1}^{N_t} \theta(t_{t_j})$
SD of Trough Angle	Standard deviation of trough angles	$\sigma_{\text{trough}} = \sqrt{\frac{1}{N_t-1} \sum (\theta(t_{t_j}) - \bar{\theta}_{\text{trough}})^2}$
Peak Slope	Slope of linear regression through peaks	$m_{\text{peak}} = \frac{\sum (t_{i_j} - \bar{t})(\theta_{i_j} - \bar{\theta})}{\sum (t_{i_j} - \bar{t})^2}$
Trough Slope	Slope of linear regression through troughs	(Same as above, applied to trough points)
Max Angular Velocity	Max first derivative of angle (deg/s)	$\omega_{\text{max}} = \max \left \frac{d\theta}{dt} \right $
Avg Max Velocity (Closing)	Average max velocity during hand closing	$\bar{\omega}_{\text{close}} = \frac{1}{N_{\text{close}}} \sum \max \left \frac{d\theta}{dt} \right $
Avg Min Velocity (Opening)	Average min velocity during hand opening	$\bar{\omega}_{\text{open}} = \frac{1}{N_{\text{open}}} \sum \min \left(\frac{d\theta}{dt} \right)$
Velocity Energy Balance	Energy ratio: closing vs. opening	$E_{\text{balance}} = \frac{\sum_{\text{closing}} \omega(t)^2}{\sum_{\text{opening}} \omega(t)^2}$
Max Acceleration	Max second derivative of angle (deg/s ²)	$\alpha_{\text{max}} = \max \left \frac{d^2\theta}{dt^2} \right $
Avg Max Accel (Closing)	Mean max acceleration during closing	$\bar{\alpha}_{\text{close}} = \frac{1}{N_{\text{close}}} \sum \max \left \frac{d^2\theta}{dt^2} \right $
Avg Min Accel (Closing)	Mean min acceleration during closing	$\underline{\alpha}_{\text{close}} = \frac{1}{N_{\text{close}}} \sum \min \left(\frac{d^2\theta}{dt^2} \right)$
Avg Max Accel (Opening)	Mean max acceleration during opening	$\bar{\alpha}_{\text{open}} = \frac{1}{N_{\text{open}}} \sum \max \left \frac{d^2\theta}{dt^2} \right $
Avg Min Accel (Opening)	Mean min acceleration during opening	$\underline{\alpha}_{\text{open}} = \frac{1}{N_{\text{open}}} \sum \min \left(\frac{d^2\theta}{dt^2} \right)$
Max Jerk	Max third derivative of angle (deg/s ³)	$j_{\text{max}} = \max \left \frac{d^3\theta}{dt^3} \right $
Avg Max Jerk (Closing)	Mean of max jerk in closing phases	$\bar{j}_{\text{close}} = \frac{1}{N_{\text{close}}} \sum \max \left \frac{d^3\theta}{dt^3} \right $
Avg Min Jerk (Closing)	Mean of min jerk in closing phases	$\underline{j}_{\text{close}} = \frac{1}{N_{\text{close}}} \sum \min \left(\frac{d^3\theta}{dt^3} \right)$
Avg Max Jerk (Opening)	Mean of max jerk in opening phases	$\bar{j}_{\text{open}} = \frac{1}{N_{\text{open}}} \sum \max \left \frac{d^3\theta}{dt^3} \right $
Avg Min Jerk (Opening)	Mean of min jerk in opening phases	$\underline{j}_{\text{open}} = \frac{1}{N_{\text{open}}} \sum \min \left(\frac{d^3\theta}{dt^3} \right)$