Supplemental Material for

Perpendicular magnetic anisotropy in a single Dy adatom ferrimagnet.

COMPUTATIONAL DETAILS

The CF matrix Δ_{CF} in Eq.(1) is obtained by projecting the self-consistent solutions of Eq.(3) into the $\{\phi_{\gamma}\}\$ local f-shell basis, giving the "local Hamiltonian"

$$\begin{split} [H_{loc}]_{\gamma\gamma'} \;\; &= \;\; \int_{\epsilon_b}^{\epsilon_t} \mathrm{d}\epsilon \, \epsilon [N(\epsilon)]_{\gamma\gamma'} \\ &\approx \;\; \epsilon_0 \delta_{\gamma\gamma'} + \left[\xi \mathbf{l} \cdot \mathbf{s} + \Delta_{\mathrm{CF}} + \frac{\Delta_{\mathrm{EX}}}{2} \hat{\sigma}_z \right]_{\gamma\gamma'} + [V_U]_{\gamma\gamma'} \,, \end{split}$$

where $[N(\epsilon)]_{\gamma_1\gamma_2}$ is the f-projected density of states (fDOS) matrix

$$[N(\epsilon)]_{\gamma_1 \gamma_2} = -\pi^{-1} \text{Im}[G(z)_{\text{DFT+U}}]_{\gamma_1 \gamma_2} ,$$

 ϵ_b is the bottom of the valence band, ϵ_t is the upper cut-off, which is naturally defined by the condition $\int_{\epsilon_b}^{\epsilon_t} d\epsilon \operatorname{Tr}[N(\epsilon)] = 14$, and ϵ_0 is the mean position of the non-interacting 5f level. The matrix Δ_{CF} is then obtained by removing the interacting DFT+U potential $[V_U]$, SOC $[\xi \mathbf{l} \cdot \mathbf{s}]$ and $\left[\frac{\Delta_{\mathrm{EX}}}{2}\hat{\sigma}_z\right]$ from H_{loc} .

The SOC parameter ξ is determined in a standard way,

$$\xi = \int_0^{R_{MT}} dr r \frac{1}{2(Mc)^2} \frac{dV(r)}{dr} (u_l(r))^2 ,$$

by making use of the radial solutions u_l of the Kohn-Sham-Dirac scalar-relativistic equations [1], the relativistic mass $M = m + (E_l - V(r))/2c^2$ at an appropriate energy E_l , and the radial derivative of spherically-symmetric part of the DFT potential.

The $\Delta_{\rm EX}$ is calculated from the energy increase ΔE by flipping a direction of 4f spin moment M_S^{4f} in the simplified DFT+U calculations with the effective spherically symmetric Coulomb $U_{eff} = U - J = 6.2$ eV, $J{=}0$ [2]. These DFT+U calculations are analogous to the so-called "open core" approximation calculations in which the direction of M_S^{Dy} with respect to the M_S^{Ni} can be designated. The $\Delta_{\rm EX} = \Delta E/M_S^{Dy}$ of 11 meV is evaluated and used in the further DFT+U(HIA) calculations.

In the DFT+U(HIA) FP-LAPW calculations, 108 special k-points in the two-dimensional Brillouin zone were used, with Gaussian smearing for k-points weighting. The "muffin-tin" radii of $R_{MT}=2.85~a.u.$ for Dy, $R_{MT}=2.20~a.u.$ for Ni, $R_{MT}=1.25~a.u.$ for C were used. The LAPW basis cut-off is defined by the condition $R_{MT}^{Dy} \times K_{max}=8.55$ (where K_{max} is the cut-off for LAPW basis set). The spin-orbit coupling (SOC) was included in a self-consistent second-variational procedure [3].

MAE FOR GR/NI(111) INTERFACE

We perform the supercell calculations for GR overlayer on the Ni(111) surface. A supercell slab model is shown in Fig. S1A which consists of a nine-layer Ni(111) substrate and GR monolayers on each side of the substrate. We consider the HCP (or "1-3") (one of the C-atoms is on the top of Ni surface, another is over the second Ni sub-surface ML) placement for graphene overlayer (GR/Ni₉/GR). The in-plane experimental Ni lattice constant of 4.7 a.u. was adopted and kept fixed in the calculations. The $d_{[C-Ni]}=3.875$ a.u. [4] separation between the carbon atoms of graphene and the topmost Ni-layer is used. A vacuum region of 20 a.u. is employed in order to reduce the slab's replica interaction along the z-direction.

We make use of the relativistic version of the full-potential linearized augmented plane-wave method (FP-LAPW) [3], in which SOC is included in a self-consistent second-variational procedure. The conventional (von Barth-Hedin) local spin-density approximation (LSDA) is adopted in the calculations, which is expected to be valid for itinerant metallic systems. The radii of the atomic muffin-tin (MT) spheres are set to 1.25 a.u. for

C atoms, and 2.2 a.u. for Ni atoms. The parameter $R_{Ni} \times K_{max} = 7.7$ defines the basis set size and the two-dimensional Brillouin zone (BZ) was sampled with 225 k points.

Spin M_S and orbital M_L magnetic MT-sphere moments are shown in Tab. I for the graphene and Ni atom layers in GR/Ni₉/GR. The moments are practically zero for the C-atoms of graphene. There is a reduction of the M_S and M_L values for the surface Ni (Ni-S) layer, indicating the interaction with the C atom of graphene on the top. In addition, there is a sizeable M_S moment of -0.15 μ_B in the interstitial.

TABLE I: Spin (M_S) and orbital (M_L) magnetic moments in the MT-sphere of the graphene and Ni atom layers (in all calculations, the magnetization is directed along the z-axis along the surface normal.) The total, and layer-resolved $T(\theta = \frac{\pi}{4}, \phi = 0)$ for GR/Ni₉/GR.

Moments (μ_B)	Graphene	Ni-S	Ni-(S-1)	Ni-(S-2)	Ni-(S-3)	Ni-(S-4)
M_S	0.01	0.48	0.55	0.59	0.60	0.60
M_L	0.00	0.04	0.05	0.06	0.05	0.06
Torque (meV)	Total	Ni-S	Ni-(S-1)	Ni-(S-2)	Ni-(S-3)	Ni-(S-4)
$T(\theta = \frac{\pi}{4}, \phi = 0)$	0.18	0.25	0.03	-0.05	-0.07	0.02

We make use of the magnetic force theorem [6] to evaluate the uniaxial magnetic anisotropy (MAE) for $GR/Ni_9/GR$. The spin magnetic moment M_S is rotated, and a single energy band calculation is performed for the new orientation of M_S . The MAE results from SOC-induced changes in the band eigenvalues $E_A(\theta, \phi) = \sum_i^{occ} \epsilon_i(\theta, \phi)$. For a hexagonal symmetry, the magnetic anisotropic energy $E_A(\theta, \phi)$ as a function of the spherical angles θ and ϕ reads,

$$E_A(\theta, \phi) = K_1 \sin^2 \theta + K_2 \sin^4 \theta + K_3 \sin^6 \theta + K_4 \sin^6 \theta \cos 6\phi ,$$
(1)

where, K_1 and K_2 are the uniaxial MAE constants, and K_3 and K_4 are the higher-order anisotropy constants [5]. In practice, it is more convenient to use the linear response theory, and evaluate the torque $T(\theta, \phi) = \partial E_A(\theta, \phi)/\partial \theta$ [7]. From the angular dependence of the torque,

$$T(\theta, \phi) = K_1 \sin 2\theta + K_2 \sin 2\theta (1 - \cos 2\theta) + \frac{3}{4} (K_3 + K_4 \cos 6\phi) \sin 2\theta (1 - \cos 2\theta)^2,$$
(2)

the uniaxial MAE constants are evaluated. An advantage of this approach is that it allows separation of the Eq.(2) into the sum of the element-specific contributions from different atoms in the unit cell [7], and to evaluate the element-specific contributions to the anisotropy constants and the total MAE. We point out that care should be taken on the convergence of the $T(\theta,\phi)$ torque Eq.(2) with respect to the two-dimensional BZ integration. For GR/Ni₉/GR case, we found that the torque value convergence better than 0.1 meV is achieved for 1521 k-points in the 2D-BZ.

The θ angular dependence of $T(\theta, \phi)$ in Eq.(2) with $\phi = 0$ is shown in Fig. 1S for GR/Ni₉/GR unit cell. Note that the $T(\theta, \phi = \pi/2)$ angular dependence is found to be very similar. In what follows, we will neglect the sixth-order anisotropy constants K_3 and K_4 , and consider only the K_1 and K_2 uniaxial anisotropies in Eq.(2). Fitting $T(\theta, \phi)$ angular dependence by Eq.(2), we obtain $K_1 = 0.21$ meV and $K_2 = -0.03$ meV per unit cell. The uniaxial MAE = $E_A[M||x] - E_A[M||z] (= K_1 + K_2) = 0.18$ meV per unit cell is evaluated. The positive MAE sign indicates the perpendicular magnetic anisotropy for GR/Ni₉/GR.

As follows from Eq.(2), the uniaxial MAE is equal to the value of $T(\theta = \frac{\pi}{4}, \phi = 0)$. The total, and layer-resolved $T(\theta = \frac{\pi}{4}, \phi = 0)$ for GR/Ni₉/GR unit cell are shown in Table S1. Note that for surface Ni (Ni-S), sub-surface Ni (Ni-(S-1)), Ni-(S-2), and Ni-(S-3) layers, these are twice the contributions from individual Ni layers in the unit cell. In Table S2, we show the layer-resolved contributions to the uniaxial MAE. The C atoms of graphene do not contribute to the total torque since their induced magnetic moments are small, and the SOC is weak. The surface Ni (Ni-S) layer contributes the most to the positive MAE. The MAE contribution from the Ni layers, which are away from the GR/Ni(111) interface is substantially smaller.

It is common to write the MAE of the ferromagnetic film as

$$MAE = d \times K_V + 2K_I,$$

where K_V is a "volume" and K_I is the $GR/Ni_9/GR$ interface contributions. Since we do not consider any strain in the Ni film, the K_V must go to zero. It is consistent with the layer-resolved MAE shown in Table S2.

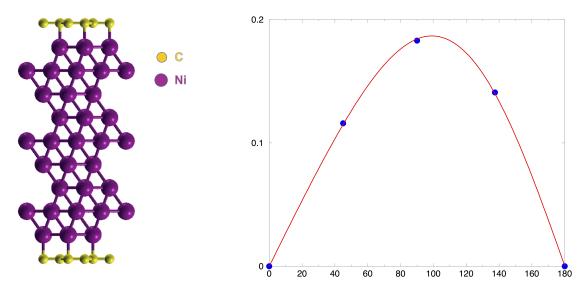


FIG. 1: A schematic crystal structure used to represent the GR/Ni₉/GR (A). The θ angular dependence of $T(\theta, \phi = 0)$ per unit cell (B).

TABLE II: The layer-resolved contributions to the MAE for GR/Ni₉/GR (meV).

MAE GR	Ni-S	Ni-(S-1)	Ni-(S-2)	Ni-(S-3)	Ni-(S-4)
(meV) 0.0	0.12	0.02	-0.03	-0.03	0.02

Additional shape anisotropy (SAE) induced by the magnetic dipole-dipole interaction can be estimated using the relation SAE = $-2\pi M^2$ to the magnetisation density M (in CGS units). This additional negative SAE of ≈ -0.008 meV per atom [9] can reduce the positive MAE. Thus, the small and positive total magnetocrystalline and shape MAE of ≈ 0.11 meV is found for GR/Ni₉/GR. Recent XAS and XMCD measurements [8] show small positive MAE for the GR/Ni(111), in a qualitative agreement with our calculations.

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