

TABLE 1: RO BASED PUF AND SENSOR TOPOLOGY

Sl. No.	Types of PUF		Methodology	Conclusion
1	RO PUF [16]		A group of RO is used to measure CRP	<ul style="list-style-type: none"> Pair of RO with lower frequency of separation led to degradation in reliability. Presence of large number of RO led to area overhead and oscillation mode of all individual RO during CRP extraction makes the power budget of RO PUF critical.
2	CRO PUF [18]		<ul style="list-style-type: none"> Similar to RO PUF, but RO section is replaced with CRO In a group of k-pair of RO, only a pair with maximum frequency separation is selected to produce reliable response bit. 	<ul style="list-style-type: none"> Enhances reliability against temperature variation. Unused pair of RO with lower frequency of separation are not considered, hence less number of CRPs. Area overhead due to added temperature compensating module.
3	Hybrid RO [25]		RO is designed by cascading positive and negative temperature co-efficient inverter to lower the frequency deviation against temperature variation.	
4	Current starved inverter based RO [26]		Family of current starved inverter with temperature invariant biasing is used.	
5	Aging compensation techniques	RO using FTL inverter [27]	FTL based inverter is used rather than conventional CMOS inverter to lower the impact of NBTI.	<ul style="list-style-type: none"> Reliability degradation due to both temperature variation and aging is improved. Area overhead due to use of additional circuit module.
6		CRO using Aging Tolerant RO (ARO) [28]	Additional NMOS per inverter is used to lower the impact of NBTI	
7		Aging Resilient Current Starved inverter based RO (ACRO) [29]	Aging compensation module includes a MUX with PMOS and NMOS to lower NBTI.	
8		CRO with reduced supply voltage [31]	The RO section is driven by a reduced supply voltage ($V_{DD} - V_t$) to lower the impact of NBTI.	
Sl. No.	Types of RO sensor		Methodology	Conclusion
1	Conventional RO sensor [13]		<ul style="list-style-type: none"> Frequency comparison between a pair of reference and stress RO predict the duration for which IC under test is used. The RO is designed by using conventional CMOS logic 	Can detect the ICs used for months
2	Accelerated Aging Mechanism	N-CDIR sensor [32]	Impact of NBTI on stress RO is accelerated by using NBTI aware RO.	Can detect the ICs used few weeks
3		AN-CDIR sensor [32]	Multiple pair of RO with NBTI accelerate feature is used as reference and stress RO rather than a single pair of RO.	Can detect the ICs used few days
4		RO sensor [34]	Voltage control section enable different amount of NBTI stress on reference and stressed RO.	Can detect the ICs used few weeks

TABLE 2 FUNCTIONAL MODE IN RO SENSOR

Mode	Function	
0	Both ROs are in sleep Mode	
1	(RO) _{STR} is in stress mode (subjected to NBTI) and (RO) _{REF} remains in sleep mode (free from NBTI)	
2	Authentication Mode (Frequency Comparison)	frequency of ROs in stress module is measured
3		frequency of ROs in reference module is measured

TABLE 3 SUPPLY VOLTAGE VARIATION IN PROPOSED INVERTER

$[C_s C_g]$	Operating voltage of RO
00	V_{DD}, V_t
01	V_{DD}, GND
10	$V_{DD}-V_t, V_t$
11	$V_{DD}-V_t, GND$

TABLE 4 FREQUENCY DEGRADATION AGAINST AGING

Types of RO	Aging Feature	% of degradation in f_{osc} after 20 year	No. of extra MOS/ inverter
Conventional CMOS RO [18]	-	26.61	-
ARO [28]	Lower NBTI	9.42	2
NBTI-aware RO [32]	Accelerate NBTI	40.81	3
RO driven by reduced supply voltage [31]	Lower NBTI	2.81	1
Proposed CRO	Lower NBTI stress ($C_s=1$)	1.111	4
	Higher NBTI stress ($C_s=0$)	45.74	

TABLE 5 PERFORMANCE COMPARISON (IN %) OF PUF

A. Security Metrics		Conventional CRO PUF [18]	ARO based CRO PUF [28]	CRO PUF with reduced supply voltage [31]	Proposed CRO PUF	Ideal value
Uniqueness		43.06	45.97	48.01	48.95	50%
Reliability	Temperature variation	91.817	-	94.54	96.984	100%
	Aging	91.284	93.322	94.421	97.825	
Uniformity		46.79	46.19	46.92	48.88	50%
SAC		47.16	46.44	47.31	49.01	50%
B. VLSI Metrics						
Power <in mW>		20.251	10.455	6.322	5.081	-
Area <in μm^2 >		656.22	782.732	398.62	292.45	-

TABLE 6 RELIABILITY AGAINST BEST AND WORST CHALLENGE PATTERN

Challenge Pattern			Temperature variation	Aging
Selection Line	$[C_{s1} C_{s2} C_{s3}]$	$[C_{g1} C_{g2} C_{g3}]$		
Worst case	[000]	[XXX]	95.18	96.011
Best case	[111]	[XXX]	99.062	99.48

TABLE 7 RELIABILITY (IN %) OF PROPOSED CRO PUF ~ NUMBER OF CRO

No. of CRO	Reliability	
	Temperature variation	Aging
64	96.984	97.825
1024	96.027	97.162

TABLE 8 PERFORMANCE COMPARISON OF RO SENSOR

Types of RO sensor	Aging duration <in Days>					Area <in μm^2 >
	T=0 D	T=2 D		T=4 D		
	μ	μ	% m	μ	% m	
AN-CDIR sensor [32]	0.384	1.847	4.56	2.266	0	9068.254
Proposed CRO sensor	0.214	2.312	1.03	3.181	0	1415.645